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Subject: Re: mvd classes

Posted by [asanchez](#) on Fri, 29 Jun 2007 09:25:19 GMT

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[quote title=Ralf Kliemt wrote on Fri, 29 June 2007 11:06]Quote:

In the Hybrid hitProducer when you ask for GetLocalHitPoint transformation , how will be the coordinates system of the silicon sensor defined? Is the same as the global frame?

GetLocalHitPoints(point, posInL, posOutL);

Takes the MvdPoint point (global frame) and converts the in and out points to the local sensor frame (written to posInL and posOutL).

Yes that i have already understood, maybe my question was not so clear, I mean

In the global frame my layers (bos xyz)

are defined in the x-z plane(horizontal), with the strips along the x-axis or along the z-axis,

So In the local frame, is this definition kept, I mean is the x-z plane in the global frame the same as in the local frame?

best regards

alicia s.

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